# **DOMENICO MURA**

#### **Automation & Robotic Engineer**

**2 February 1987** 

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# **EXPERIENCE**

#### PhD Fellow

#### University of Pisa, Department of Information Engineering

Movember 2018 - Ongoing

Pisa, PI

- PhD Course in Information Engineering
- Research Field: Robotics and Automation

#### **Fellow**

#### **Italian Institute of Technology**

🛗 January 2018 - October 2018

- ♀ Genoa. GE
- Research line: Soft Robotics for Human Cooperation and Rehabilitation
- Cooperative and Continuative Collaboration

### Scientific Collaborator

#### Research Center E. Piaggio

 Team working on my master thesis device improvements and on the robotic hand pose reconstruction problem

### **PUBLICATIONS**

### Journal Articles

- Mura, Domenico, Espen Knoop, et al. (2020). "On the role of stiffness and synchronization in human-robot handshaking". In: The International Journal of Robotics Research.
- Mura, Domenico, Cosimo Della Santina, et al. (2019). "Exploiting Adaptability in Soft Feet for Sensing Contact Forces". In: IEEE Robotics and Automation Letters 5.2, pp. 391–398.
- Mura, Domenico, Manuel Barbarossa, et al. (2018). "A Soft Modular End Effector for Underwater Manipulation: A Gentle, Adaptable Grasp for the Ocean Depths". In: IEEE Robotics & Automation Magazine 25.4, pp. 45–56.

# **PROJECTS**

#### Socio-Physical Interaction Skills for Cooperative Human-Robot Systems in Agile Production (SOPHIA)

**1/12/19 - 30/11/23** 

- SOPHIA has received funding from the European Union's Horizon 2020 Research and Innovation Programme (H2020-ICT-2019-2/ 2019-2023) under grant agreement No. 871237
- Project site: https://project-sophia.eu/

# SUMMARY

Currently a PhD Fellow in Information Engineering, graduated in Automation and Robotic Engineering with a master thesis on soft robotic manipulation.

Robotics, and its impact on our life and health, has always fascinated me, even when I was a biomedical engineering student. My current research interests consist in sensorization of soft robotic devices and in underwater manipulation for archaeological/biological tasks.

# **LANGUAGES**

Italian English



# **STRENGTHS**

Matlab/Simulink C/C++

Model Based Design ROS

PTC Creo CAD Rapid Prototyping

Communication/Presentation Skills

Positive Attitude | Love of Learning

Creative Problem Solving

**Teamwork** 

LaTeX

# **EDUCATION**

M.Sc. in Robotic and Automation Engineering

Università di Pisa

**2014 - 2017** 

**110/110** 

# B.Sc. in Biomedical Engineering Università di Pisa

**#** 2007 - 2014

**9** 90/110

Classical High School Diploma
L. Cl. Giorgio Asproni

**#** 2001 - 2006

**9** 94/100

